

A Note on Flag Curvature in Finsler Space

Indiwar Singh Chauhan¹, T.S. Chauhan², Pankaj Kumar Sharma³, Mohammad Gauhar⁴

Assistant Professor, Bareilly College, Bareilly, (U.P.), ²Associate Professor, Bareilly College, Bareilly, (U.P.), ³Principal, Baba Ramdas P.G. College, Bareilly(U.P.), ⁴Research Scholar, IFTM University, Moradabad(U.P.) Corresponding Author: Indiwar Singh Chauhan

Date of Submission: 25-02-2022

Date of Acceptance: 28-02-2022

ABSTRACT: This paper has been devoted to the study of Finsler space with flag curvature. Section 1 is devoted to the study of theory of indicatrix. Section 2 delineates to the non-linear connections. Section 3 is metric devoted to the study of flag curvature in Finsler space.

KEYWORDS: Minkowski space, C-projective, Flag curvature, Finsler space.

I. INTRODUCTION

Let Mⁿ be a Minkowski space with the indicatrix $F(X^{i}) = 1$, wherein $X^{i}(i = 1, 2, 3, ---, -, -)$ n) may be regarded as components of a vector. The indicatrix $F(X^{i}) = 1$ is given by $X^{i} = X^{i}(u^{\alpha})$ with n-1 parameters $u^{\alpha}(\alpha = 1, 2, 3, \dots, n-1)$ that is to say, we shall regard the indicatrix as an (n-1)-dimensional manifold I^{n-1} with coordinate system (u^{α}) . The indicatrix is given by [4]:

 $F^{2}(X) = g_{ii}(X) X^{i}X^{j} = 1,$ (1.1)

If the Minkowski space Mⁿ be a Riemannian space with the metric tensor given by $g_{ij}(X)$, then the induced metric tensor $g_{\alpha\beta}(u)$ on the indicatrix I^{n-1} is given by [4]:

(1.2)
$$g_{\alpha\beta} = g_{\alpha\beta}(u) = g_{ij} X^{i}{}_{\alpha} X^{j}{}_{\beta}$$

Wherein

 $X^{i}_{\alpha} = (\Box X^{i} / \Box u^{\alpha}).$ (1.3)

Differentiating equation (1.1) by u^{α} and using equation (1.3), we get

 $g_{ij} X^i_{\alpha} X^j = 0$ (1.4)

This equation shows that the vector X¹ is normal unit vector of Iⁿ⁻¹.

The covariant derivative of X^{i}_{α} and using D-symbol, we get [6]:

(1.5) $D_{\alpha} X^{i}_{\beta} = H^{i}_{\alpha\beta},$ $D_{\alpha} X^{j}_{\ \beta} = h_{\alpha\beta} X^{i}$ (1.6)and

 $\mathbf{D}_{\alpha}\mathbf{X}^{i}_{\beta} = \Box_{\alpha}\mathbf{X}^{i}_{\beta} + \{ \begin{smallmatrix} i \\ j \\ k \end{smallmatrix} \} \mathbf{X}^{j}_{\alpha}\mathbf{X}^{k}_{\beta} - \{ \begin{smallmatrix} \gamma \\ \alpha \\ \beta \end{smallmatrix} \} \mathbf{X}^{i}_{\gamma}.$ (1.7)

equation Differentiating (1.4)covariantly and using D-symbol, we obtain $g_{ij}X^{i}_{\alpha}X^{j}_{\beta} + g_{ij}(D_{\beta}X^{i}_{\alpha})X^{j} = 0$ (1.8)and $g_{\alpha\beta} + h_{\alpha\beta} = 0.$ (1.9)By virtue of equations (1.2) and (1.8)yields $g_{\alpha\beta} + g_{ij}(D_{\beta}X^{i}{}_{\alpha})X^{j} = 0$ (1.10)From equations (1.6) and (1.10), we get $g_{\alpha\beta} + g_{ij} h_{\beta\alpha} X^i X^j = 0,$ (1.11)In view of equations (1.1) and (1.11), we obtain (1.12) $g_{\alpha\beta} + h_{\beta\alpha} = 0,$ Comparing equations (1.9) and (1.12)vields $h_{\alpha\beta} = h_{\beta\alpha}$, (1.13)Hence, $h_{\alpha\beta}$ is symmetric tensor of I^{n-1} . In view of equations (1.2) and (1.9), we obtain $h_{\alpha\beta} = - g_{ij} X^i{}_{\alpha} X^j{}_{\beta}$ (1.14)Contracting equation (1.9) with $g^{\alpha\gamma}$, we obtain $g^{\alpha\gamma}h_{\alpha\beta} = - \Box^{\gamma}{}_{\beta}$ (1.15)Contracting equation (1.9) with $g^{\alpha\beta}$

yields (1.16)

II. METRIC NON-LINEAR

CONNECTIONS Consider a differentiable vector field Xⁱ in a Finsler space F^n , and there is given a set of functions $\prod_{k=1}^{1i} (x,X)$ depending on this field, wherein $\Gamma^{1i}_{k}(x,X)$ are homogeneous of degree one in the Xⁱ. Then absolute differential is defined as

 $\delta X^i = dX^i + \Gamma^{1i}_{k}(x,X)dx^k$ (2.1)

 $g^{\alpha\gamma}h_{\alpha\beta} = -(n-1).$

DOI: 10.35629/5252-040215991602 Impact Factor value 7.429 | ISO 9001: 2008 Certified Journal Page 1599



Next, consider a covariant vector field Y_i in Finsler space Fⁿ. Then the the absolute differential of Y_i is defined as $\Box Y_i = dY_i - \Gamma^2_{ik}(x, Y) dx^k$ (2.2)Wherein $\Gamma^2_{ik}(x,Y)$ is homogeneous of degree one in Y_i. Let us consider a relation between X¹ and Y_i is (2.3) $Y_i = g_{ij}X^j$, Contracting equation (2.3) by X^{i} and using equation (1.1), we get (2.4) $X^{1} Y_{i} = 1$, The absolute differential δY_i coincides with the covariant component of δX^i , i.e. $\delta Y_i = g_{ij} \, \delta X^J$ (2.5)Consequently yields $\Gamma^{2}_{ik}(\mathbf{x},\mathbf{Y}) = (\partial g_{ij}/\Box \mathbf{x}^{k})\mathbf{X}^{j} - g_{ij}\Gamma^{1i}_{k}(\mathbf{x},\mathbf{X}).$ (2.6)Next, we shall find out another form of the coefficients $\Gamma^{1i}_{\ k}$ and $\Gamma^{2}_{\ jk}$. The following equation in F(x,X) is (2.7) $\mathbf{F}_{,\mathbf{k}} = (\partial \mathbf{F} / \Box \mathbf{x}^{\mathbf{k}}) - (\partial \mathbf{F} / \Box \mathbf{X}) \mathbf{G}_{,\mathbf{k}}^{\mathbf{j}}(\mathbf{x},\mathbf{X}) = 0$ Wherein $G^{j}_{,k}(x,X) = (\partial G^{j}/\partial X^{k})$ (2.8)and $G^{i}(x,X) = (1/2) \{ {}^{i}_{hk} \} X^{h} X^{k}.$ (2.9)From equations (2.1) and (2.7), we have $\Gamma^{1i}_{k}(x,X) = T^{i}_{k}(x,X) + G^{i}_{k}(x,X),$ (2.10)Wherein $T_{k}^{i}(x,X)$ is an arbitrary homogeneous of degree one in X¹ tensor which satisfies the relations $g_{ij} X^i T^j_k = 0$ (2.11)and $B_{i}^{i}T_{k}^{j} = T_{k}^{i}$. (2.12)Therefore, we take
$$\begin{split} \Gamma^2_{\ jk}(x,Y) &= T^*{}_{jk}(x,Y) + G^i{}_{,jk}(x,\phi(x,Y))Y_i, \\ \text{Wherein} \quad T^*{}_{jk} \quad \text{is an arbitrary tensor} \end{split}$$
(2.13)homogeneous of degree one in Yi which is restricted by the relation $T^*_{jk} X^j = 0$. In view of equations (2.10) and (2.13), the equation (2.6) assumes the form (2.14) $T^*_{jk}(x,Y) = -g_{ij}T^i_k + \{(\partial g_{ij}/\partial x^k)X^i - g_{ij}G^i_k G^{i}_{,jk}Y_{i}$ But $g_{ii}G^{i}_{,k}X^{j} = (1/2)(\partial g_{im}/\partial x^{k})X^{j}X^{m}$ (2.15) $= g_{ij}X^{j} \left(\{ {}^{i}_{m\,k} \} X^{m} - \{ {}^{j}_{m\,n} \} C^{i}_{kl} X^{m} X^{n} \right),$ Differentiating equation (2.15) by X^h yields $(\partial g_{hm}/\partial x^k)X^m = g_{ih}G^i_{,k} + Y_iG^i_{,kh},$ (2.16)Inserting equation (2.16) the in equation (2.14), we obtain $T^*_{jk} = -g_{ij}T^i_{k}$. (2.17)Since (2.18) $T_{ik} = g_{ii}T_{k}^{i}$. Using equation (3.18) in the equation (2.17), we get

(2.19) $T^*_{jk} = -T_{jk}$. **Theorem 2.1:**

If the coefficients $\Gamma^{2h}_{\ jk}$ of a relative connection parameters is symmetric with indices j and k then the tensor T_{jk} is also symmetric with indices j and k.

Proof:

In view of equations (2.13) and (2.19), we obtain

 $(2.20) \quad \Gamma^{2}_{jk}(x,Y) = -T_{jk}(x,\phi(x,Y)) \\ G^{i}_{,ik}(x,\phi(x,Y))Y_{i},$

Interchanging the indices j and k in equation (2.20), we get

(2.21) $\Gamma^{2}_{kj}(x,Y)$

 $T_{kj}(x,\phi(x,Y))+G^{i}_{,kj}(x,\phi(x,Y))Y_{i},$

Since $\Box I_{jk}^2(x, Y)$ is symmetric with j and k, then equation (2.21) reduces in the form

From equations (2.20) and (2.22), we obtain

(2.23) $T_{jk} = T_{kj}$,

Hence, $T_{jk}\ \text{is symmetric with indices }j$ and k.

III. FLAG CURVATURE IN FINSLER SPACE

If M is an n-dimension C^{∞} space and F is the Finsler metric then we assume that $F^n(M,F)$ be a Finsler space. F is assumed to be a C^{∞} function on the slit tangent bundle $TxM^o = TxM \setminus \{0\}$ satisfying the condition:

(a) F is C^{∞} on TxM°

(b) F(x,ky) = k F(x,y), for any $x \in M, y \in T_x M$ and k > 0

(c) $g_{ab} = (1/2) \{ \partial^2 F^2 / \partial y^a \partial y^b \},$

is positive definite at every point (x,y) of TxM° . It is to be noted that (x^{a},y^{b}) are the coordinates on TxM where (x^{a}) are the coordinates on M. $(\partial \Box \partial x^{a} \Box \partial \Box \partial \overline{y})$ is the local fram field on TxM. Then the Liouville vector field (3.1) $L = y^{a}(\partial \Box \partial y^{a})$

is defined as a global section of the vertical vector bundle TxM°.

Further, (3.2) L = 1 Fis a unit vector field,

(3.3) $g_{ab} \square l^b = 1$,

Wherein

(3.4) $l^a F = y^a$.

Now, Let us assume a flag yAu at x \in M determined by y and u= u^a($\partial \Box \partial x^a$). Flag curvature is first used by L. Berwald [3]. The flag curvature for the flag yAu is the number[2,1]: (3.5) K = (R_{ab}u^au^b)/{(g_{ab}u^au^b) - (g_{ab}y^au^b)²}.

DOI: 10.35629/5252-040215991602 Impact Factor value 7.429 | ISO 9001: 2008 Certified Journal Page 1600



Flag curvature K must be constant when the flag curvature K depends neither on y^a nor on u^a. Also it is well known that Fⁿ has constant flag curvature K iff (3.6) $R_{ab} = K h_{ab}$, Wherein h_{ab} are the components of the angular metric on F^n defined by (3.7) $\mathbf{h}_{ab} = \mathbf{g}_{ab} - \mathbf{l}_a \mathbf{l}_b$. The Riemannian curvature tensor of Berwald connection is defined as $K^{a}_{\ bcd} \ = \ \lambda_{c}G^{a}_{\ bd} \ + \ G^{e}_{\ bd}G^{a}_{\ ec} \ - \ \lambda_{d}G^{a}_{\ bc} \ +$ (3.8) $G^{e}_{\ bc}G^{a}_{\ ed}.$ If we take (3.9) $K^a_{bc} = K^a_{0bc}$ and $K^{a}_{b} = K^{a}_{0b},$ (3.10)Consequently, yields $\mathbf{K}^{\mathbf{a}}_{\mathbf{b}\mathbf{c}} = (1/3)(\dot{\partial}_{\mathbf{b}}\mathbf{K}^{\mathbf{a}}_{\mathbf{c}} - \dot{\partial}_{\mathbf{c}}\mathbf{K}^{\mathbf{a}}_{\mathbf{b}}).$ (3.11) The projective Weyl curvature is expressed as follows [7,8]: $W^{a}_{bcd} = K^{a}_{bcd} + \{1/(n^{2}-1)\}\{\delta^{a}_{b}(\dot{K}_{dc}-\dot{K}_{cd})\}$ (3.12) $+ \,\delta^a_{d}\dot{K}_{bc}^{c}\,\bar{\delta}^a_{c}\dot{K}_{bd} + F\,l^a\,\dot{\partial}_b(\dot{K}_{dc}^{c}\,\dot{K}_{cd}),$ Wherein (3.13) $\dot{\mathbf{K}}_{ab} = \mathbf{n}\mathbf{K}_{ab} + \mathbf{K}_{ba} + \mathbf{F} \mathbf{l}^{e} \,\dot{\partial}_{a}\mathbf{K}_{be}.$ It is noteworthy that a Finsler metric is one of scalar flag curvature iff $W^{a}_{bcd} = 0.$ (3.14)Let us consider a mapping $\phi : F^n \to F^n$ and ϕ be diffeomorphism. Then ϕ is said to be a projective

diffeomorphism. Then ϕ is said to be a projective mapping if there exists a positive homogeneous scalar function P of degree one satisfying the relation

 $(3.15) \quad G^{a} = G^{a} + FP l^{a},$

Wherein P is the projective factor [9].

Under a projective transformation with projective factor P, the Riemannian curvature tensor of Berwald connection change is given by the following expression

 $(3.16) \quad \check{K}^{a}_{bcd} = K^{a}_{bcd} + Fl^{a} \partial_{b}Q_{cd} + \delta^{a}_{b}Q_{cd} + \delta^{a}_{c} \partial_{b}Q_{d}$ $- \delta^{a}_{d} \dot{\partial}_{b}Q_{c},$

Wherein

- $(3.17) \qquad Q_a = \lambda_a P P P_a \\ and \qquad \qquad$
- $(3.18) \qquad Q_{ab} = \dot{\partial}_a Q_b \dot{\partial}_b Q_a.$

It is noted that if $Q_{ab} = 0$ then a projective transformation with projective factor P is said to be C-projective.

(3.19) $\pounds_{X}G^{a}_{bcd} = \delta^{a}_{b}P_{cd} + \delta^{a}_{c}P_{bd} + \delta^{a}_{d}P_{cb} + Fl^{a}P_{bcd}$ and

 $\begin{array}{l} (3.20) \quad \ \ \, \pounds_X K^a_{\ bcd} = \delta^a_{\ b} (P_{d!c} - P_{c!d}) + \delta^a_{\ d} \, P_{b!c} - \delta^a_{\ c} \, P_{b!d} \\ + F I^a \, \dot{\partial}_b (P_{d!c} - P_{c!d}). \end{array}$

(3.21) Since $Q_{bc} = P_{b!c} - P_{c!b},$ We have [5,7]:

$$(3.22) \quad \partial_{a} P_{b!c} = P_{ab!c} - P_{e} G^{e}_{abc},$$

Contracting a and c in (3.21), yield (3.23) $\pounds_X K_{bd} = P_{d!b} - nP_{b!d} + F P_{bd!h}l^h$,

- $\begin{array}{c} (3.23) \\ L_X \mathbf{K}_{bd} = \mathbf{I}_{d!b} \mathbf{II}_{b!d} + \mathbf{I}_{l} \mathbf{I}_{bd!} \\ \text{Hence, obtain} \\ (2.24) \\ L_X \mathbf{K}_{bd} = \mathbf{I}_{d!b} \mathbf{II}_{b!d} + \mathbf{I}_{l} \mathbf{I}_{bd!} \\ \end{array}$
- (3.24) $\pounds_{X}(Fl^{e}\dot{\partial}_{d}K_{be}) = (n-1)F P_{bd!h}l^{h},$ Consequently yields
- (3.25) $\pounds_X(K_{bd} + \{1/(n+1)\}Fl^e \dot{\partial}_d K_{be}) = P_{d!b} nP_{b!d}$ and
- $\begin{array}{rll} (3.26) & \pounds_X(K_{db} \ + \ \{1/(n+1)\}Fl^e \ \dot{\partial}_b K_{de}) \ = \ P_{b!d} \ nP_{d!b}, \end{array}$

As a consequence of equations (3.25) and (3.26), we get

If $Q_{ab} = 0$, the equation (3.20) reduces to

(3.28) $\pounds_{\mathbf{X}} \mathbf{K}^{\mathbf{a}}_{\mathbf{bcd}} = \delta^{\mathbf{a}}_{\mathbf{d}} \mathbf{P}_{\mathbf{b}!\mathbf{c}} - \delta^{\mathbf{a}}_{\mathbf{c}} \mathbf{P}_{\mathbf{b}!\mathbf{d}},$

By virtue of equations (3.27) and (3.28), we obtain new type of tensor

 $\begin{array}{l} (3.29) \quad \dot{W}^{a}_{bcd} = K^{a}_{bcd} - \{1/1 - n^{2}\} [\hat{\delta}^{a}_{d} \{ \dot{K}_{bc} \\ +\{n/(n+1)\} \quad Fl^{e}(\dot{\partial}_{c}K_{be} - \dot{\partial}_{b}K_{ce}) \} + \delta^{a}_{c}\{ \dot{K}_{bd} + \{n/(n+1)\} Fl^{e}(\dot{\partial}_{d}K_{be} - \dot{\partial}_{b}K_{de}) \}], \end{array}$

As a consequence of

- $(3.30) \quad l^a l^e \,\dot{\partial}_b K_{ae} = 0$
- and
- (3.31) $\dot{W}^{a}_{c} = \dot{W}^{a}_{bcd} l^{b} l^{d}$.

We obtain

(3.32) $\dot{W}_{c}^{a} = K_{c}^{a} - \{1/(1-n^{2})\}[Fl^{a} \dot{K}_{0c} - \delta_{c}^{a} \dot{K}_{00}].$

The tensor K is called C-projective Weyl curvature. If C-projective Weyl-curvature is vanish then a Finsler metric F is called C-projective Weyl metric.

In view of above discussions, we have the following theorems:

Theorem 3.1:

Let F be a C-projective Weyl metric. Then prove that F is a Weyl metric.

Proof:

Let us assume that

(3.33) $K^{a}_{c} - \{1/(1-n^{2})\}[Fl^{a}\dot{K}_{0c} - \delta^{a}_{c}\dot{K}_{00}] = 0,$

Contracting (3.33) by l^a yields

- $(3.34) \quad F^3 \, \dot{K}_{0c} l_c \, \dot{K}_{00} = 0,$
- (3.35) Consequently, $\dot{K}_{0c} = F^{-3} l_c \dot{K}_{00},$
- By virtue of equations (3.33) and (3.35), we obtain

(3.36) $K^{a}_{c} = \{1/(1-n^{2})\}h^{a}_{c}\dot{K}_{00},$

Consequently F is said to be scalar flag curvature. Therefore F is a Weyl metric.

Theorem 3.2:

Let F be a Finsler metric of scalar flag curvature κ . Then C-projective Weyl curvature is defined as $\dot{W}^{a}_{c} = (1/3)F^{3}l^{a}\kappa_{c}$, wherein $\kappa_{c} = \dot{\partial}_{c}\kappa$. **Proof:**

The Riemannian curvature of Berwald connection is given by[3]:

DOI: 10.35629/5252-040215991602 Impact Factor value 7.429 | ISO 9001: 2008 Certified Journal Page 1601



 $K^{a}_{\ bcd} = \kappa (\delta^{a}_{\ c}g_{bd} - \delta^{a}_{\ d}g_{bc}) + \kappa_{b}F(\delta^{a}_{\ c}F_{d} -$ (3.37) $\delta^a_d F_c$) + $(1/3)[F^2(h^a_c\kappa_{bd}-h^a_d\kappa_{bc})+\kappa_dF(2\delta^a_cF_b-2\delta^a_bF_c)$ - $g_{bc}l^a$) + $\kappa_c F(2\delta^a_d F_b - 2\delta^a_b F_d - g_{bd}l^a)$, Wherein (3.38) $\kappa_{\rm bc} = \dot{\partial}_{\rm c} \kappa_{\rm b}.$ Consequently yields (3.39) $K^{a}_{b} = \kappa F^{2} h^{a}_{b}$ As a consequence, we obtain [9]: (3.40)2)($F^2 \kappa_{bd}$ + 2FF_b κ_d), $\dot{K}_{00} = (n^2 - 1)\kappa F^2$, (3.41) $K_{0c} = (n-1)\kappa FF_c + (1/3)(n-2)F^2\kappa_c$ (3.42) $\dot{K}_{0c} = (n^2 - 1)(\kappa FF_c + (1/3)F^2\kappa_c)$ (3.43)By virtue of equations (3.32), (3.39), (3.41) and (3.43), we obtain

(3.44) $\dot{W}^{a}_{c} = (1/3)F^{3}l^{a}\kappa_{c}$.

Theorem 3.3:

If F is a Finsler metric of constant flag curvature with $K = \kappa$. Then F is C-projective Weyl metric. **Proof:**

If F is of constant flag curvature κ then equation (3.37) reduces in the form (3.45) $K^{a}_{bcd} = \kappa (\delta^{a}_{c}g_{bd} - \delta^{a}_{d}g_{bc}),$

(5.45) $\mathbf{K}_{bcd} = \mathbf{K}(\mathbf{0}_{c}\mathbf{g}_{bd} - \mathbf{0}_{d}\mathbf{g}_{bc}),$ Yields

(3.46) $K_{bd} = -(n-1)\kappa g_{bd}$, and

(3.47) $\dot{K}_{bd} = -(n^2 - 1)g_{bd}$,

By virtue of equations (3.29), (3.46) and (3.47) yields

(3.48) $\dot{W}^{a}_{bcd} = 0,$ Consequently yields

(3.49) $\dot{W}^{a}_{c} = 0.$

In Finsler metric F of scalar flag curvature with dimension $n \ge 3$, we have a projective transformation with the projective factor P, we have the following conditions:

 $\begin{array}{ll} (3.50) & \dot{S}_{ab} = S_{ab} + \{(n\!+\!1)\!/\!2\} P_{ab}, \\ \text{and} & \end{array}$

(3.51)
$$\dot{S}_{eb}\dot{G}^{e}_{a} = S_{eb}G^{e}_{a} + PS_{ab} + \{(n+1)/2\}(P_{eb}G^{e}_{a} + PP_{ab}).$$

In view of above discussion, we have the following:

Theorem 3.4:

 $\overline{\tau}$ -curvature is C-projective invariant. **Proof:** For a projective transformation, we have (3.52) $\dot{\tau}_{ab} = F\dot{S}_{abc}l^c$, By virtue of equations (3.50), (3.51) and (3.52) yields Consequently follows

(3.54) $Fl^e \dot{\partial}_a Q_{bc} = Fl^e \lambda_e P_{ab} - P_{eb} G^e_a - P_{ea} G^e_b,$ From equations (3.53) and (3.54), we get

(3.55) $\dot{\tau}_{ab} = \tau_{ab} + \{(n+1)/2\} F l^e \dot{\partial}_a Q_{be},$

If we take C-projective mapping i.e. $Q_{ab} = 0$. Follows

(3.55) $\dot{\tau}_{ab} = \tau_{ab}$.

Hence, $\boldsymbol{\tau}$ -curvature is C-projective invariant.

REFERENCES

- Bacso, S. and Papp, I. (2004), "A note on generalized Douglas space." Periodica Mathematicia Hungarica, 48 (1-2), 181-184.
- [2]. Bao, D., Chem, S.S. and Shen, Z. (2000), "An introduction to Riemann-Finsler geometry." Graduate Text in Math, Springer, Berlin, 200.
- Berwald, L. (1926), "UberParallelubertragung in Raumenmit allgemeiner Massbestimmung, Jber. Deutsch. Math-Verein. 34, 213-220.
- [4]. Kawaguchi, A. (1956), "On the theory of non-linear connections II, Theory of Minkowski space." Tensor, N.S., 6, 165-199.
- [5]. Najafi, B., Shen, Z. and Tayebi, A. (2008), "Finsler metrics of scalar flag curvature with special non-Riemannian curvature properties." Geom. Dedicata, 131, 87-97.
- [6]. Schouten, J.A. and Struik, D.J. (1938), "Einfuhruing in die neueren Methoden der Differential geometric." P.Noordhoff N.V.
- [7]. Shen, Z. (2001), "Differential Geometry of Spray and Finsler Spaces." Kluwer Academic Publishers, Dordrecht.
- [8]. Shen, Z. (2003), "Projectively flat Finsler metrics of constant flag curvature." Transactions of the American Mathematical Society, 355, 4, 1713-1728.
- [9]. Singh, S.P. (2010), "Projective motion in bi - recurrent Finsler space." Diff. Geom. Dyn. Syst. 12, 221-227.